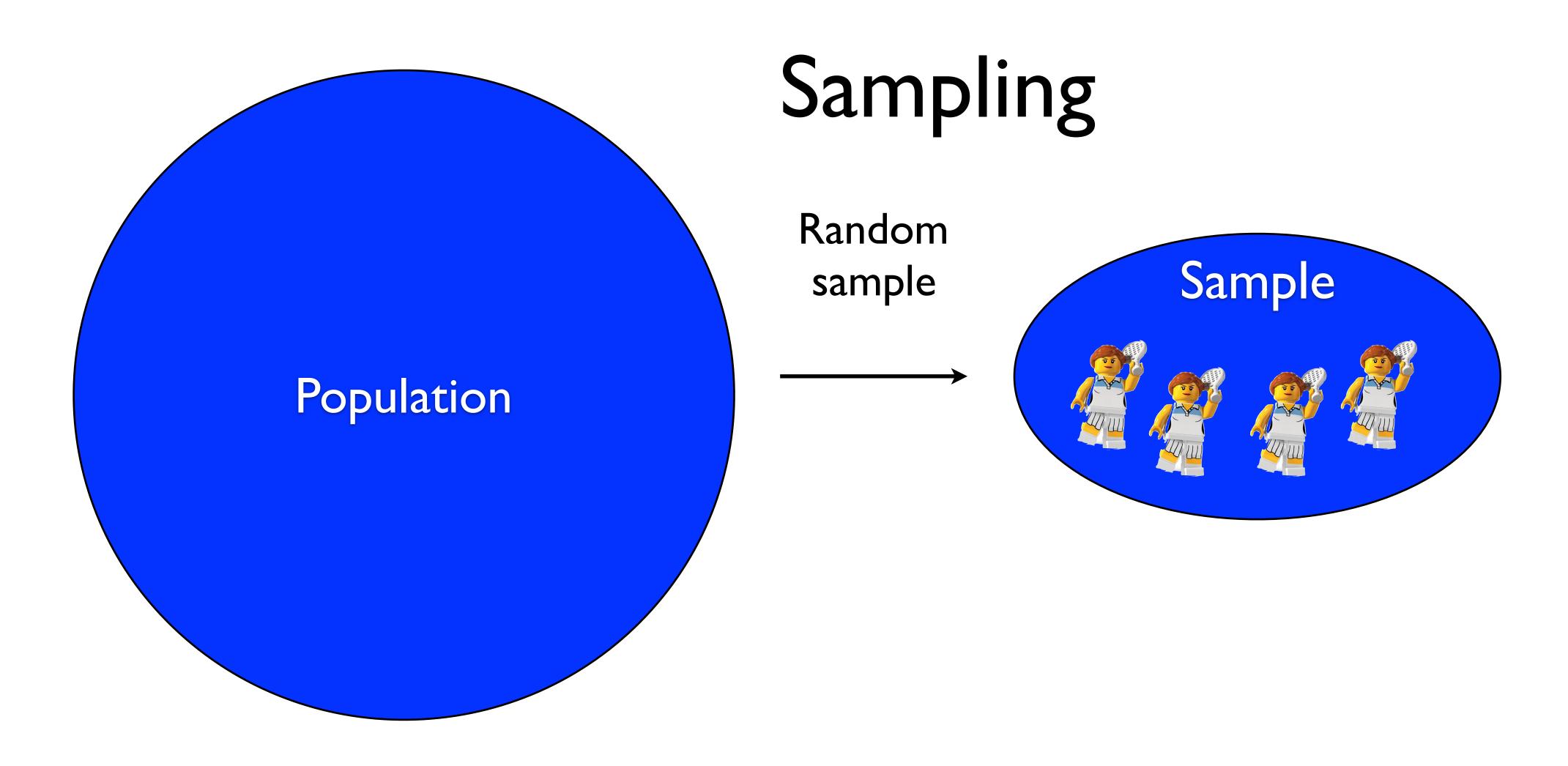
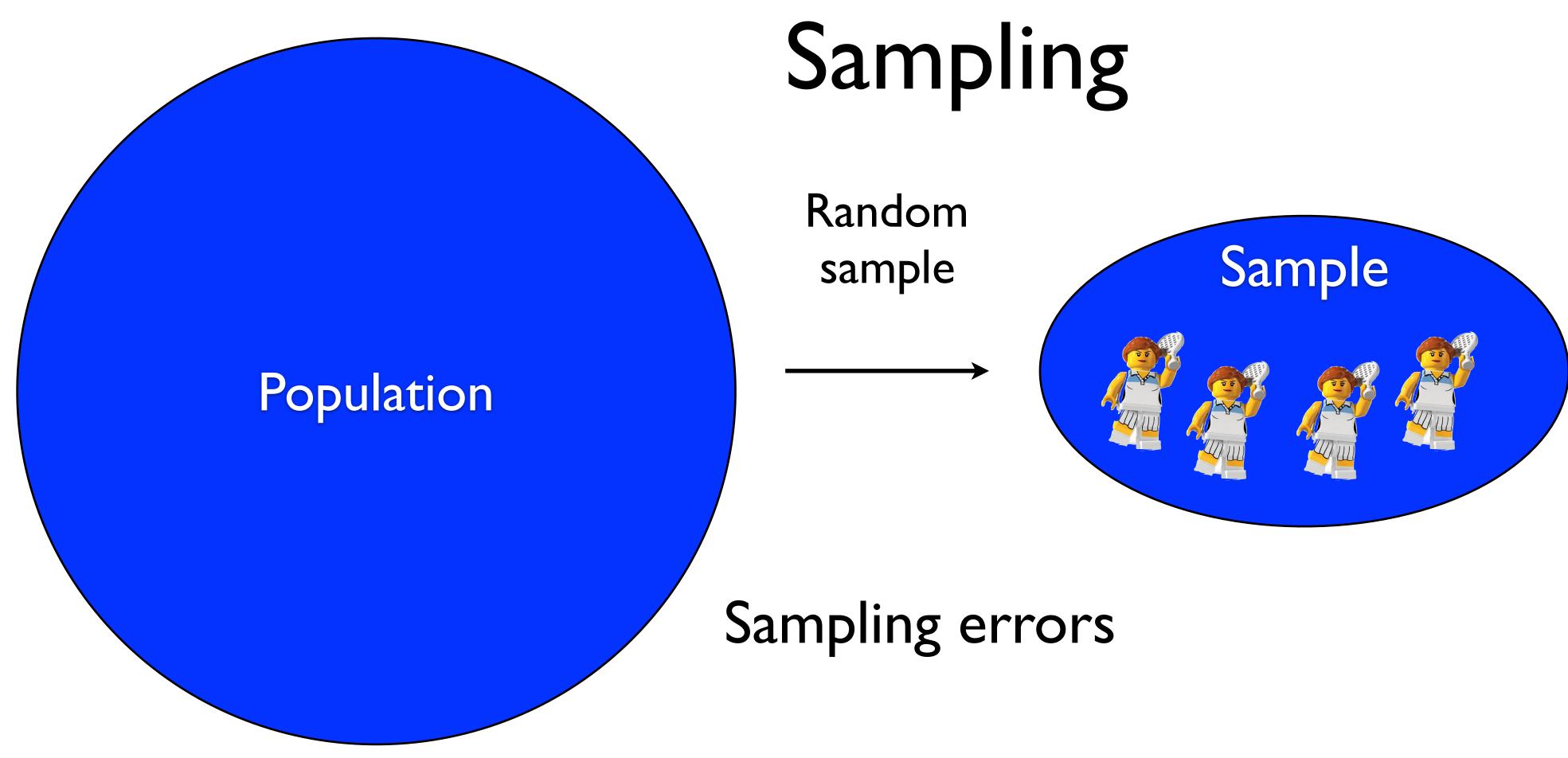


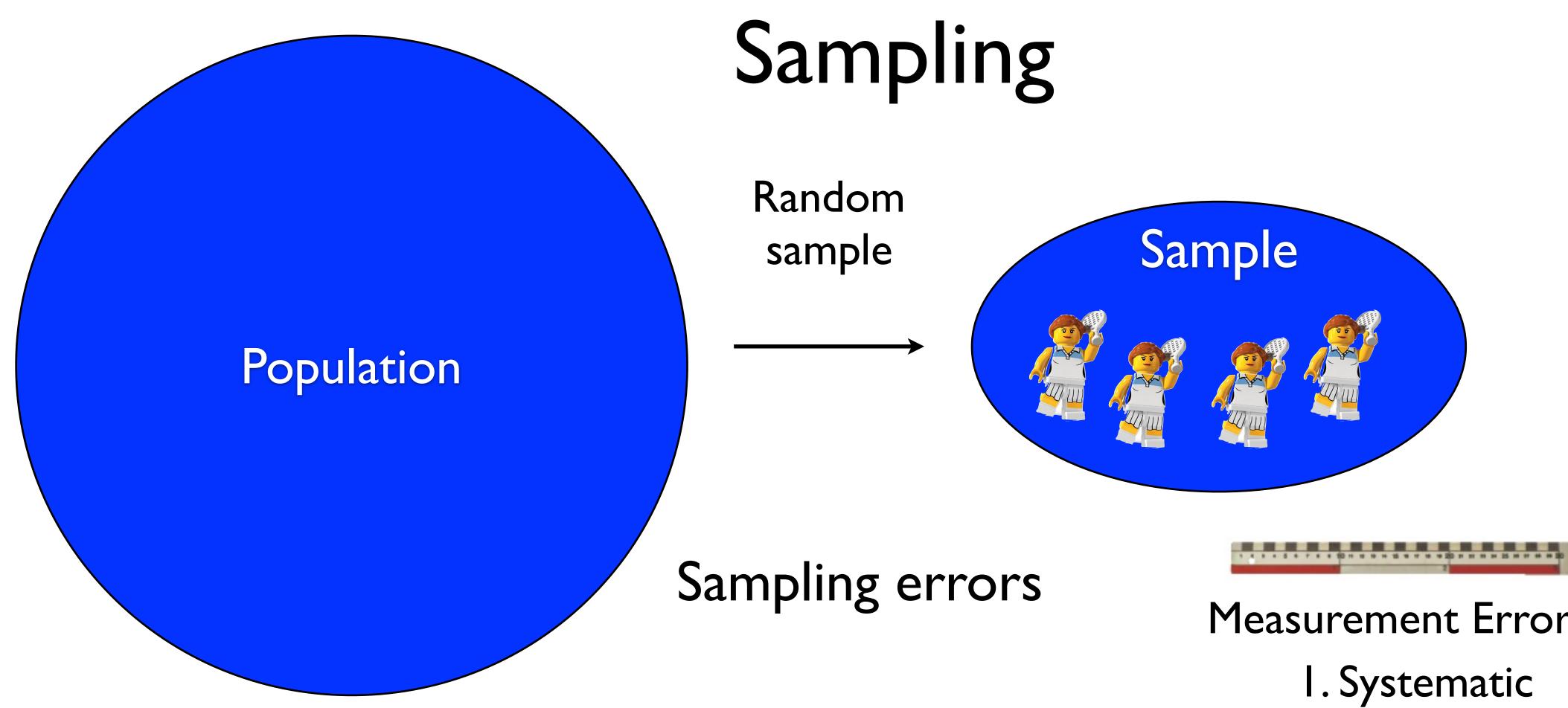
Hypothesis Testing CB2030 Lukas Käll, KTH





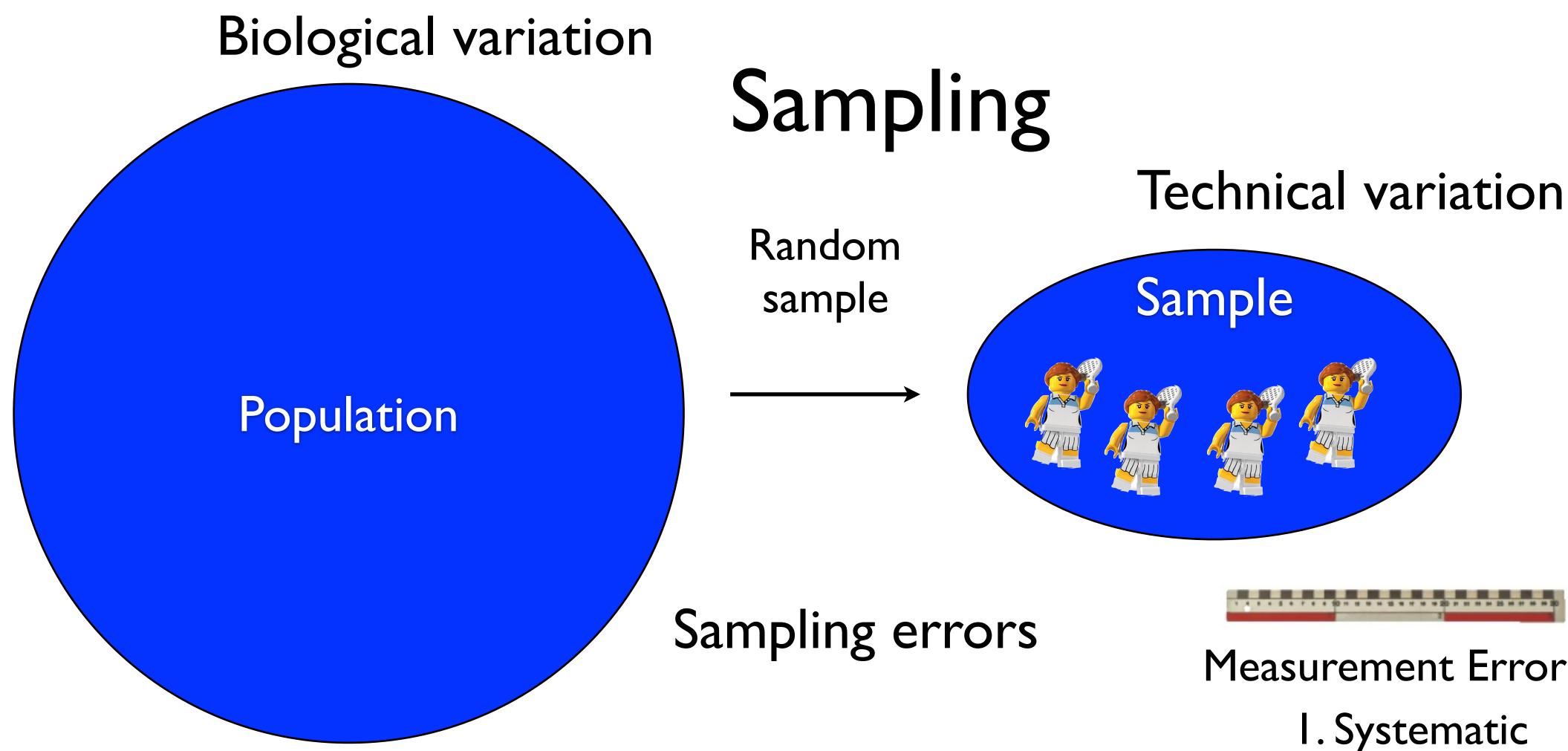






Measurement Errors

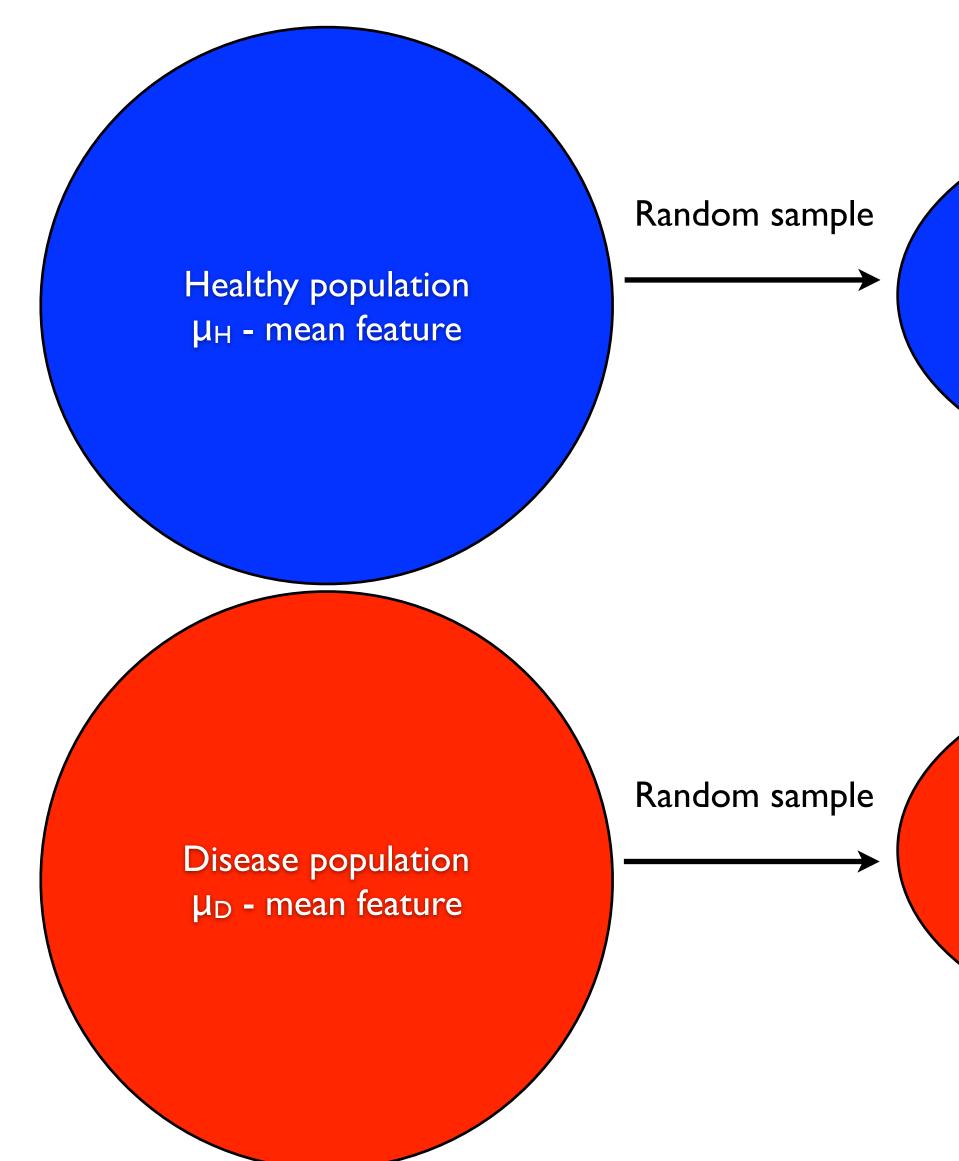
2. Noise

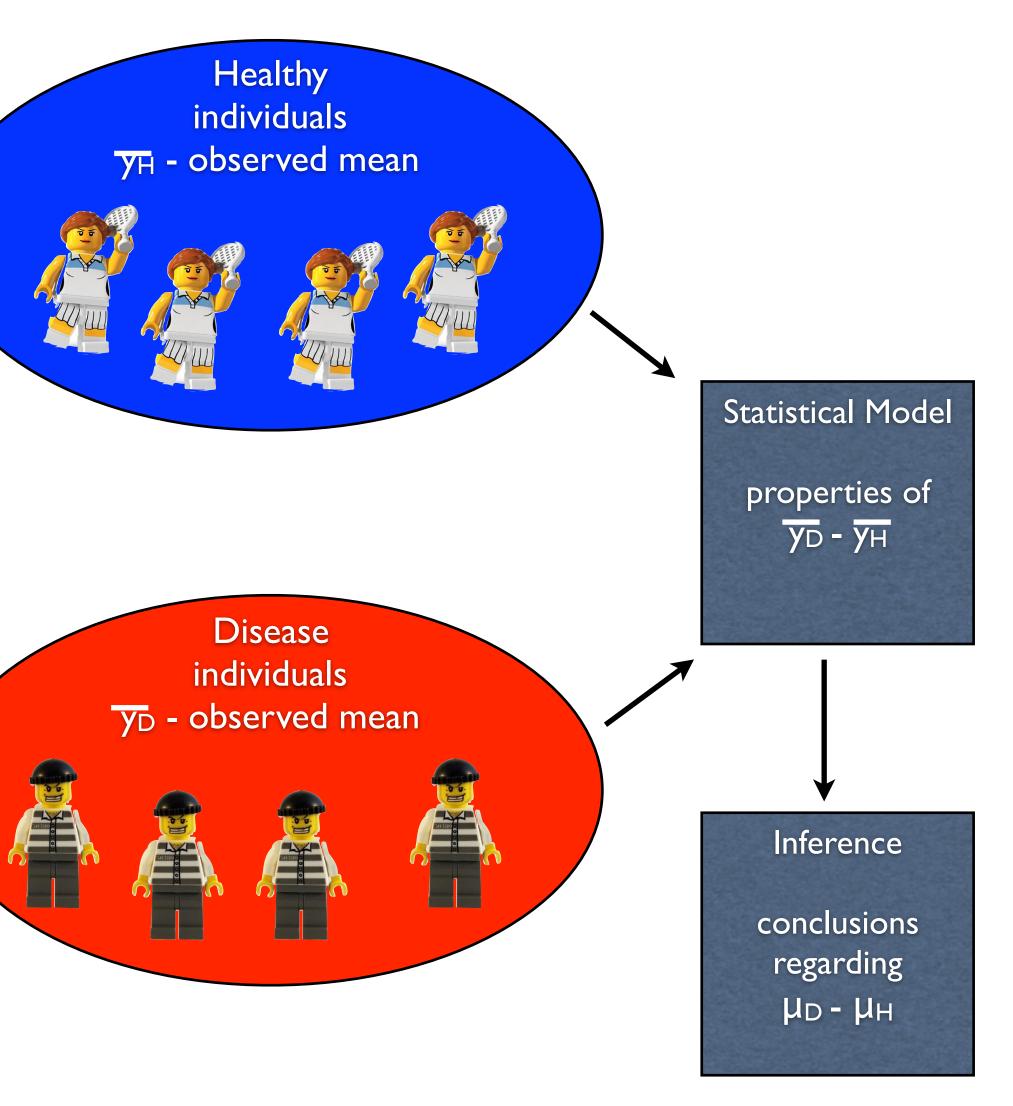


Measurement Errors

I. Systematic 2. Noise

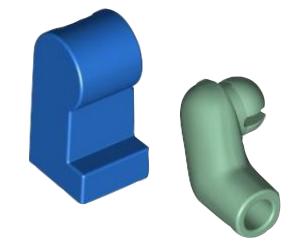
Statistical inference procedure





Our Hypotheses

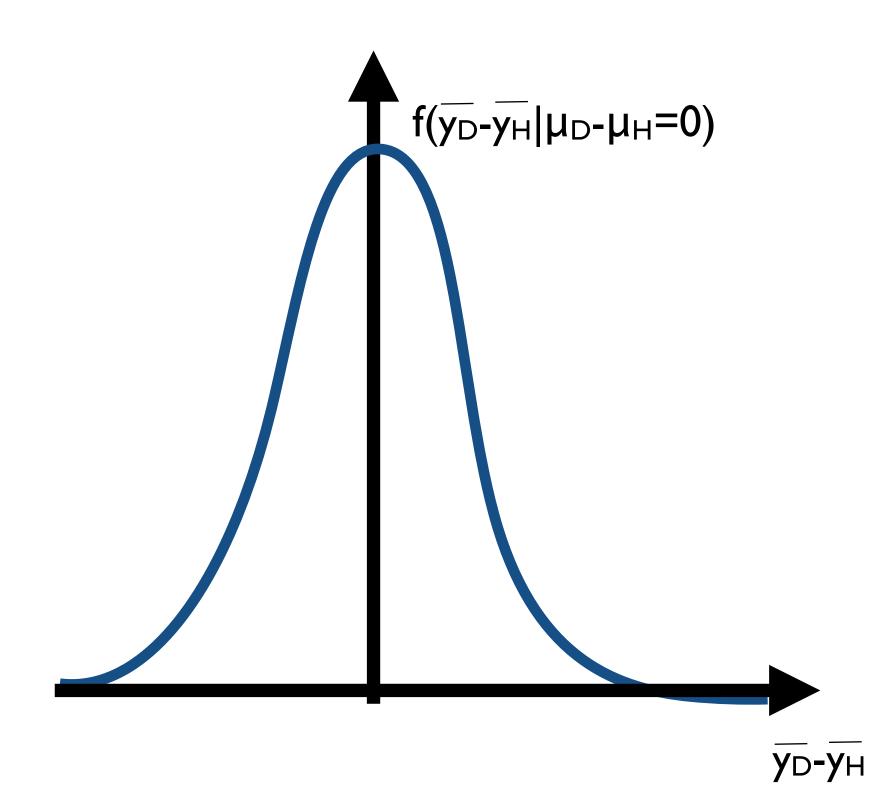
- H_0 : The null hypothesis. The situation we are not interested in (typically $\mu_D - \mu_H = 0$)
- H_I : The alternative hypothesis. The situation we want to detect (typically $\mu_D - \mu_H \neq 0$)





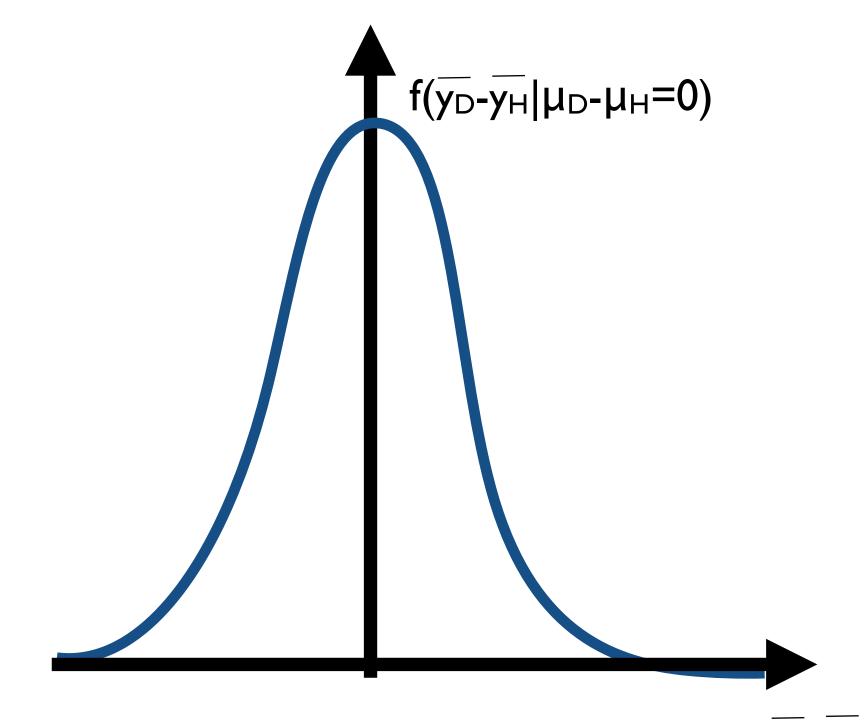
 The distribution of any statistic of measurements in a sample, e.g. its mean, is known as a sampling distribution

Sampling Distribution



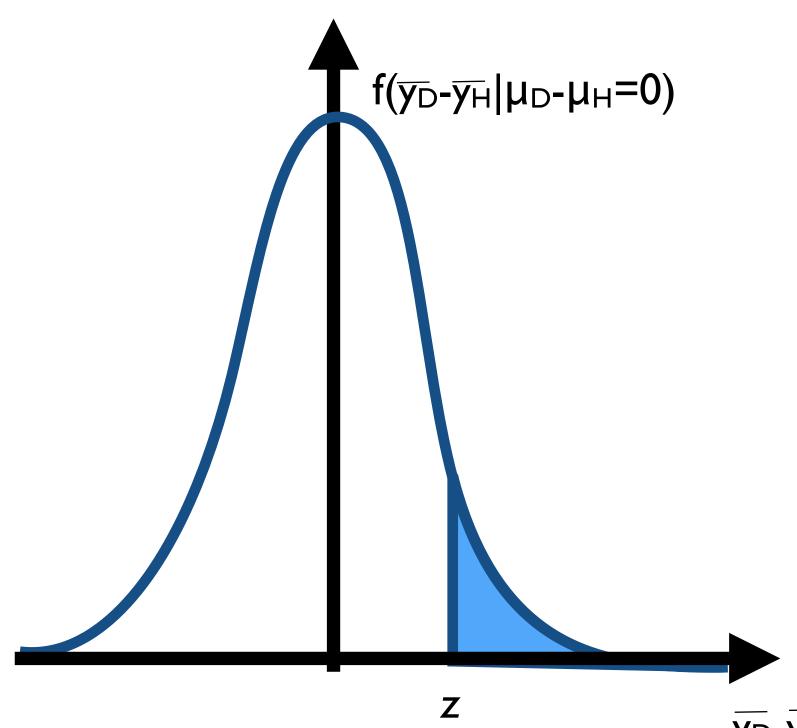
- The distribution of any statistic of measurements in a sample, e.g. its mean, is known as a sampling distribution
- If we know the sampling distribution of the difference in sample mean under H_0 we can calculate how extreme the difference is.

Sampling Distribution



Vn-Vu ירן ען

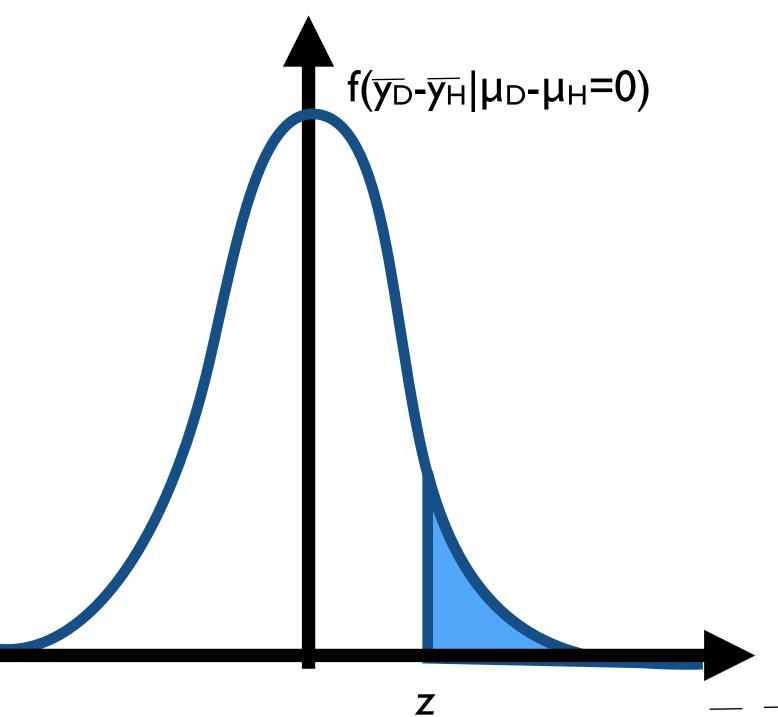
p value



ур**-у**н

• $\Pr(\bar{y}_D - \bar{y}_H \ge z | \mu_D - \mu_H = 0)$, *i.e.* the probability of a result at least as extreme as the one that was observed, given $H_{0,j}$ is known as a one-sided p value.

p value



ין ען

- $\Pr(\overline{y}_D \overline{y}_H \ge z | \mu_D \mu_H = 0)$, *i.e.* the probability of a result at least as extreme as the one that was observed, given H_{0} , is known as a one-sided p value.
- $\Pr(|\bar{y}_D \bar{y}_H| \ge z |\mu_D \mu_H = 0)$ is known as a two-sided p value.

p value

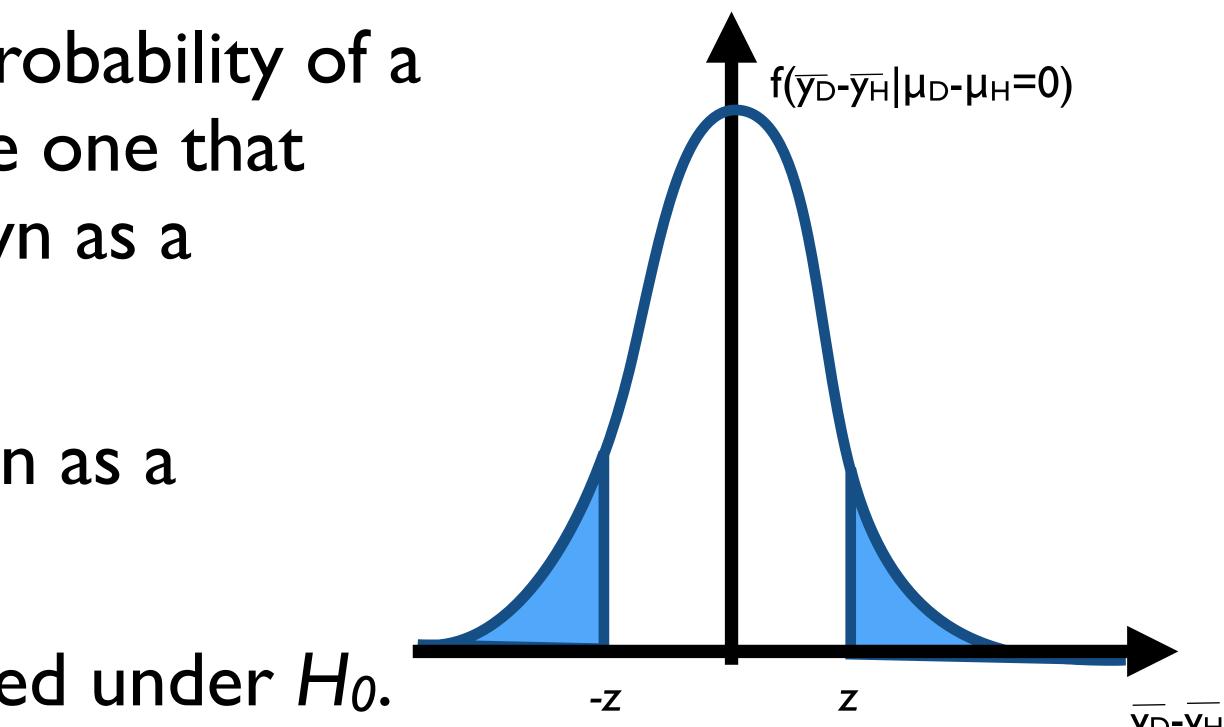
f(у_D-у_H|µ_D-µ_H=0)

Ζ

JDJH

- $\Pr(\overline{y}_D \overline{y}_H \ge z | \mu_D \mu_H = 0)$, *i.e.* the probability of a result at least as extreme as the one that was observed, given H_{0} , is known as a one-sided p value.
- $\Pr(|\overline{y}_D \overline{y}_H| \ge z |\mu_D \mu_H = 0)$ is known as a two-sided p value.
- p values are uniformly distributed under H_0 .

p value



JDJH

Statistical inference procedure

